15 days

to

PDR

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/lassA	Senior Des	ign Project -
	Home	Teams

nior Desi	gn Project -	SDP19
Home	Teams	Syllabus

Schedule

Schedule

This schedule shows the main events for SDP19. Please note that the schedule is subject to change.

Lectures

Examples

		Se	ptember 2	018		
Sun	Mon	Tue	Wed	Thu	Fri	Sat
						1
2	3	4 First day of classes	5	6	7	8
9	10 Lecture 1: Introduction	11	12	13	14	15
16	17 Lecture 2: Problem Specification and Team Management	18	19	20	21 Advisors due	22
23	24 Lecture 3: PDR	25	26 Benchside Meetings	27	28	29

October 2018						
Sun	Mon	Tue	Wed	Thu	Fri	Sat
30	1 Benchside Meetings	2	3	4	5	6
7	8 Holiday	9 PDR	10 PDR	11 PDR	12 PDR	13
14	15 PDR	16 PDR	17 PDR	18 PDR	19 PDR	20
21	22	23	24	25	26	27

Benchside Meetings

Benchside	e Meeting	Benchside Meeting		
Wed 26th	Sept 2018	Mon 1st Oct18		
location:	SDP lab	location: SDP lab		
Time (pm)	Team	Time (pm)	Team	
5:30	Team 13	4:30	Team 3	
5:45	Team 10	4:45	Team 26	
6:00	Team 7	5:00	Team 23	
6:15	Team 4	5:15	Team 20	
6:30	Team 1	5:30	Team 17	
6:45	Team 27	5:45	Team 14	
7:00	Team 24	6:00	Team 11	
7:15	Team 21	6:15	Team 8	
7:30	Team 18	6:30	Team 5	
7:45	Team 15	6:45	Team 2	
8:00	Team 12	7:00	Team 25	
8:15	Team 9	7:15	Team 22	
8:30	Team 6	7.30	Team 19	
			Team 16	

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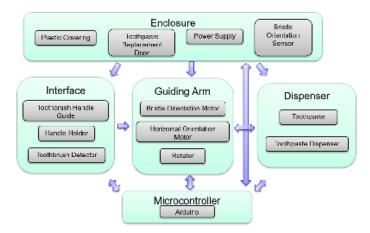
Place 'n Paste (Team #xy) Benchside Meeting 26th September 2018

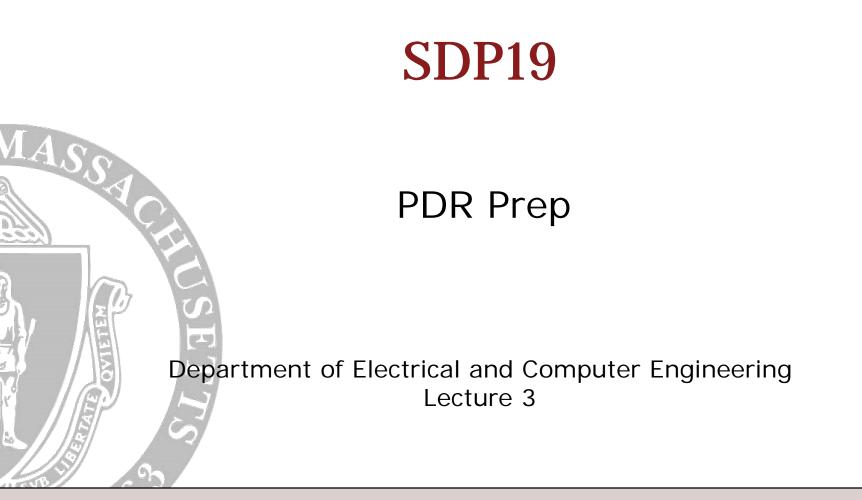
Problem Statement: Students with severe disabilities face many challenges with tasks that we perform every day with little thought. For one student in the "Life Skills" program in West Springfield schools, his limited fine motor skills make it impossible for him to squeeze tooth paste onto his tooth brush. Our "Place and Paste" system will offer him independence by allowing him to brush his teeth without assistance. An easy-loading system will secure the toothbrush, move it under the toothpaste, squeeze the toothpaste, and present the toothbrush for use.

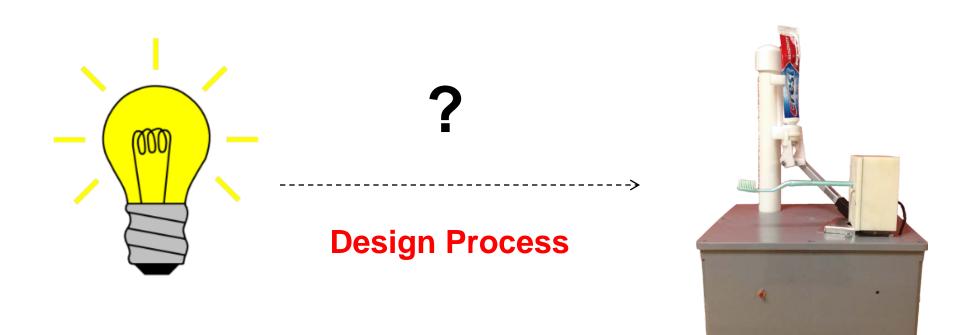
System Specifications:

- 1. Dispense pea-sized toothpaste onto brush
- 2. Will hold toothbrush such that the machine and toothbrush will stay sanitary
- Toothbrush will be placed in a way such that users lacking fine motor skills can insert toothbrush
- Product will take no longer than 20 seconds from when toothbrush is correctly inserted to return loaded toothbrush
- 5. Product size will not obstruct normal use of school's single occupancy bathroom
- Product will be designed such that it will guide toothbrush motion once it is placed into holder

Block Diagram:

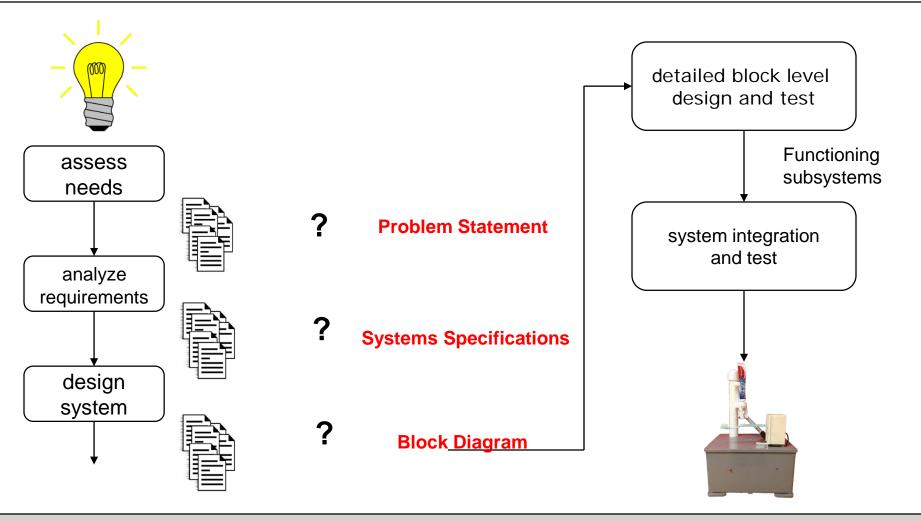






"Place and Paste" SDP12

Design Process: Set Intermediate Goals



Covering the Fundamentals of PDR

- We will examine a previous PDR presentation
 - Covers all major points
 - Well executed presentation for a useful project
 - Place N Paste Senior Design Project 2012 Salvatore Cacciatore, Kenny Neyhart, Benjamin Oven, Tony Saloio
- You need to describe what you have done so far and what you will do in the future
 - Ask *yourself* the tough questions first before evaluators do
- Stress teamwork and moving forward together

PDR Preparations

- Your presentation must address
 - Assess needs (Problem Statement)
 - Analyze requirements (System Specifications)
 - Design System (Design Alternatives & Solution: Block Diagram)
 - Team roles (technical and administrative)
- MDR Deliverables
 - Very specific
 - What will your prototype be able to do?
 - Focus on most essential, technically challenging portion of project
- Handouts (1 per reviewer)
 - Problem statement/System Specifications/Block diagram
 - Copy of slides (~4 slides/page printout)
- Budget

UMassAmherst PDR Rules

- 20 Minutes of Presentation
- Evaluators May Not Interrupt Presentation
- Evenly Divided Among Team Members
- Advisor Present but Silent
- 20 Minutes of Questions & Answers
- Invited guests may also be present
- Evaluators will forward evaluation to your SDP adviser.

PDR Questions



Is your project impressive?

- Significant?
- Societal Impact?





Do your reviewers have advice?

What will you deliver for MDR?

Practice, Practice, Practice



Four speakers is 20 minutes is a lot of handoffs. Practice at least 2 times in front of advisor.

Assess Needs (Problem Statement) – Place n Paste

- Assess Needs
 - 1. Students cannot properly squeeze toothpaste
 - 2. Unable to apply appropriate amount of toothpaste
 - 3. Teachers must assist students every time they need to brush
 - 4. Students must be independent in maintaining *their* daily hygiene
- Problem Statement
 - 1. Difficult for disabled people to brush their teeth without assistance
 - 2. Automated system that doesn't make a mess. Easy to use
 - 3. Functioning system that can easily be used by a disabled person without external assistance

Analyze Requirements (System Specifications)

- 1. Dispense pea-sized toothpaste onto brush
- 2. Will hold toothbrush such that the machine and toothbrush will stay sanitary
- 3. Toothbrush will be placed in a way such that users lacking fine motor skills can insert toothbrush
- 4. Product will take no longer than 20 seconds from when toothbrush is correctly inserted to return loaded toothbrush
- Product size will not obstruct normal use of school's single occupancy bathroom
- 6. Product will be designed such that it will guide toothbrush motion once it is placed into holder

Design Alternatives (Existing Products)

This product will not meet:

Specification 3: Toothbrush will be placed in a way such that users lacking fine motor skills can insert toothbrush

Specification 6: Product will be designed such that it will guide toothbrush motion once it is placed into holder



Design Alternatives (Existing Products)

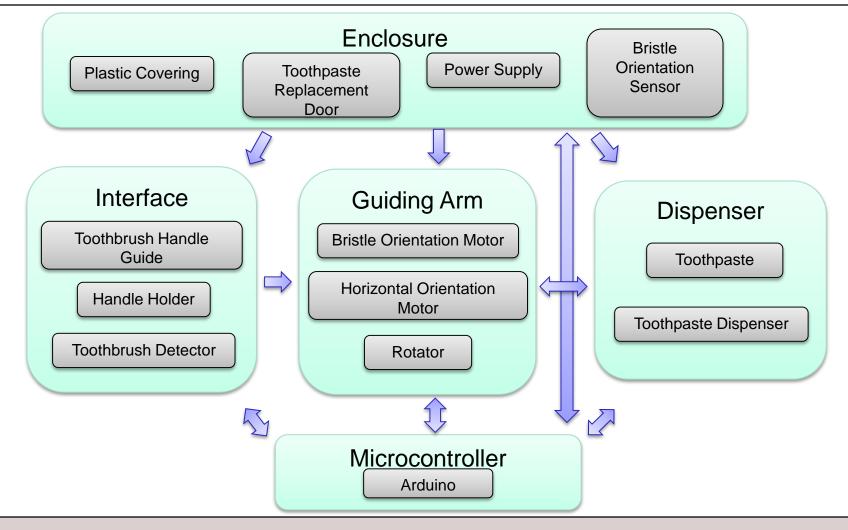
This product will not meet:

Specification 2: Will hold toothbrush such that the machine and toothbrush will stay sanitary

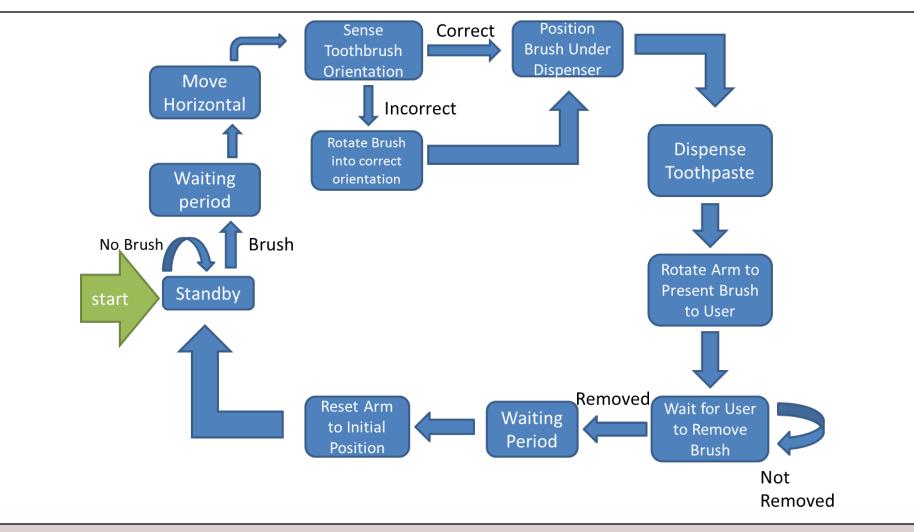
Specification 3: Toothbrush will be placed in a way such that users lacking fine motor skills can insert toothbrush



Solution: Block Diagram



Solution: State Machine



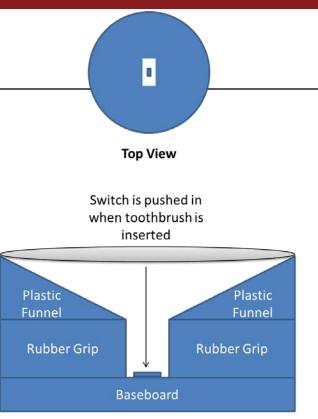
Subsystem: Microcontroller

- Satisfies requirement 4
- Arduino Uno
- Controls all motors and sensors
- Controls timing of operations
- Easily programmable
- Digital and analog inputs and outputs
- Contains onboard clock

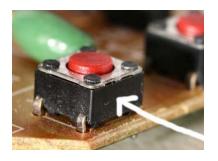


Subsystem: Interface

- Satisfies requirement 3
 - Plastic funnel allows for guided entry into grip
- Helps satisfy requirement 2
 - Direct contact only with handle of brush
- Rubber grip holds toothbrush in place while allowing easy entry and exit
- Micro switch indicates toothbrush detection

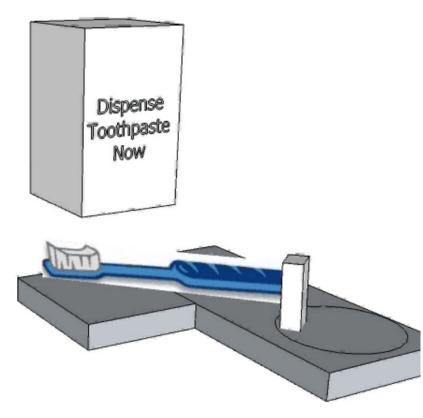






Subsystem: Guiding Arm

- Satisfies requirement 6
 - Once activated toothbrush is fully guided through motion
 - Limits user involvement to initial insertion and final removal
- Uses Servo motors to control motion
 - Compact
 - Easy to Use
- Helps satisfy requirement 2
 - Controls motion for minimum surface contact



Subsystem: Dispensing

- Satisfies requirement 1
 - COTS dispensing product designed to dispense proper amount of toothpaste
- Helps satisfy requirement 2
 - Toothbrush does not come into contact with dispenser
- Uses Servo Motor to control Dispensing
- Will dispense toothpaste only when toothbrush is in correct position



Subsystem: Enclosure

- Need enclosure to house all products
- Plugged into wall for power
- Helps with requirement 2
 - Limits access to dispensing mechanism
- Allows for easy replacement of empty toothpaste tube
- Keeps electronics, motors, and other components out of direct contact
- Helps satisfy requirement 3
 - Allows for easy toothbrush insertion and removal
- Satisfies requirement 5
 - Compact enough to fit into confined space in bathroom

Subsystem: Additional Features

- Time Permitting:
 - Sound indicators for proper toothbrush insertion and removal
 - LED indicator to show low toothpaste supply
 - Programmable timer to help encourage proper brushing for students
 - Light and Music integration
 - Network interface to notify teacher of low toothpaste
 - Work for a wider range of toothbrush sizes

Products: Budget

- COTS Toothpaste Dispenser: \$25.00
- Toothpaste: \$5.00
- Arduino Microcontroller \$35.00
- Interface Product: \$50.00
 - Funnel
 - Rubber Holder
 - Microswitch
- Motor/Servo
 - 4x \$40.00 = \$160.00
- Proximity Sensor: \$70.00
- Enclosure: \$150.00
 TOTAL: \$495.00

Subsystems: Risks

- Hardware
 - Custom Designed Enclosure
 - Third Party COTS Dispenser
 - Many moving parts
- Software
 - Arduino working with chosen sensors
 - Proper timing of motors crucial to success

MDR Deliverables

- Prototype of basic movement
 - Starts in horizontal Position
 - Moves guiding arm to specific location
 - Dispenses toothpaste

This slide is not sufficient.

- It should include a figure
- More details of what specifically will be shown

Other Slides You Need

- Breakdown of activities for each student
 - Each student should discuss their responsibilities
 - Each student should be able to answer questions regarding their approach
- What will you present at FPR and at Demo Day
 - Be prepared to answer questions about this.
 - A drawing would be helpful
 - Be realistic

Other Suggestions

- 1. Have a friend or family member review your slides.
- 2. Practice by asking each other questions
- 3. Wear nice clothes. Easier to be taken seriously
- 4. Have fun! Think of it as a performance rather than a presentation

PDR Rubric

UMass	SDP18 PDR – Evaluation Sheet	Team Number/Name	
Team Member	Si		
Evaluators:			
Presentation (15%)	 (4.0) A professional presentation that demonstrates knowledge and practice. (3.5) The presentation should have been practiced more. (3.0) The presentation was confusing at a few points. (2.5) The presentation was confusing at more than a few points. (2.0) The presentation was poorly organized or presented. 		
Problem Statement (10%)	 (4.0) Project's background, design and deliverables described in straightforward and non-technica (3.5) A few necessary characteristics of the problem statement are missing. (3.0) More than a few characteristics are missing. (2.5) Problem statement given, but is either inappropriate of very incomplete (2.0) Minimal emphasis was placed on the problem statement. 	al terms.	
System Specs (25%)	 (4.0) Requirements are clear, complete, quantitative and appropriate. (3.5) A few necessary requirements are missing or unclear. (3.0) More than a few requirements are missing. (2.5) Requirements are given, but they are either inappropriate or very incomplete. (2.0) Minimal emphasis was placed on requirements. 		
Design Alternatives (10%)	(4.0) Technical and non-technical alternatives were described and compared well.		
Block Diagram (25%)	 (4.0) A clear block diagram, well defined interfaces, and feasible plan to implement. (3.3) One or two blocks is poorly defined or feasibility is unknown. (2.7) More than two blocks are missing interface or feasibility. (2.0) The block diagram needs major work. 		
 (4.0) Deliverables address the most essential, technically challenging portion of project. Individual responsibilities addressed. (3.3) Either the most essential portion of the project or individual responsibilities were not fully addressed. (2.7) Both the most essential portion of the project and individual responsibilities were not fully addressed. (2.0) Both the most essential portion of the project and individual responsibilities were not addressed. 			

PDR Rubric

UMass SDP18 PDR – Evaluation (Written Comments)	Team Number/Name
Team Members:	
Evaluators:	
Presentation	
Problem Statement	
System Specs	
System Specs	
Design Alternatives	
Block Diagram	
MDR Deliverables	
Other Comments:	

Scheduling a PDR

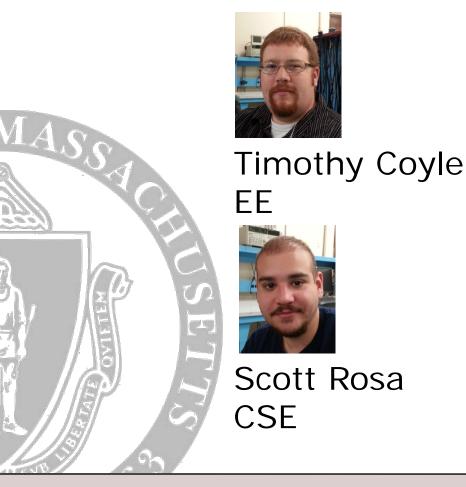
Preliminary Design Review

Team RCA October 15, 2012

Department of Electrical and Computer Engineering

Advisor: Professor Hollot

RCA (Real-Time Concussion Analyzer)





Kenneth Van Tassell EE



Justin Kober EE

Department of Electrical and Computer Engineering

Advisor: Professor Hollot

Concussion Detection in High School Football

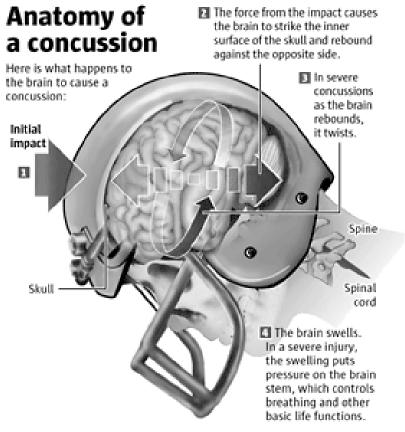


- Current concussion detection
 - Train coaches to recognize symptoms
- Players may hide or not experience symptoms right away

How significant is the problem?

- 1.6 3.8 million sports-related concussions in the United states every year
 - Have reached "epidemic level"
- Not only professionals
 - Young people ages 15 24 years
 - Second leading cause of TBI (Traumatic Brain Injury)

Context: Effect on Individuals



Sources: Dr. Jay Rosenberg of Koiser Permanente Medical Care Neurology; American Academy of Neurology; The Human Body

MARK NOWLIN / THE SEATTLE TIMES

- Post Concussion Syndrome
 - Problems concentrating, irritability, sensitivity to light...
- If gone undiagnosed
 - One hit away from traumatic brain injury
 - Multiple impacts add up

Context: Effect on Groups

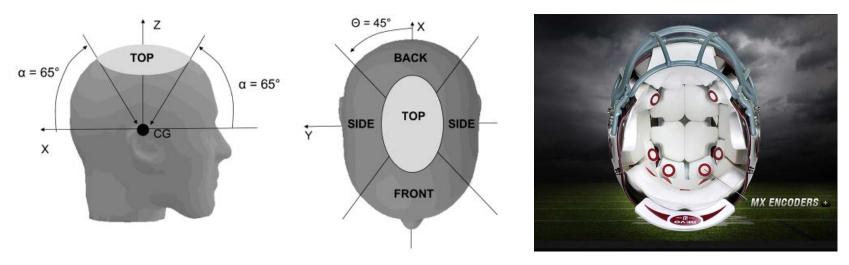
- Affects team sports and the way they're played
- "Tough guy attitude"
 - Creates a culture
- Subjective decision making

Requirements Analysis: Specifications

- Real-Time continuous impact measurements
- Player specific adaptability
- Equipment weight increase less than 5%
- Effective range 150 m
- Responds in under two seconds
- Robust
 - Interference
 - Durable

Design Alternatives

- HITS Head Impact Telemetry System †
 - Six accelerometers
 - Frequency, location, and magnitude
 - Sideline response system
 - Linear acceleration



†Measuring Head Kinematics in Football: Correlation Between the Head Impact Telemetry System and Hybrid III Headform. Beckwith, Jonathan, Jeffrey Chu, and Richard Greenwald. October 13th 2011

Design Alternatives

- ShockBox
 - Impakt Protective
 - Commercial use for football/hockey
 - Secured with high adhesive bonding tape
 - Wireless transmission
 - Threshold of 50 g set by app
- HEADS
 - BAE Systems
 - Military use
 - Suspended beneath the crown of the helmet
 - Wireless/USB transmission
 - Processing done by computer at base



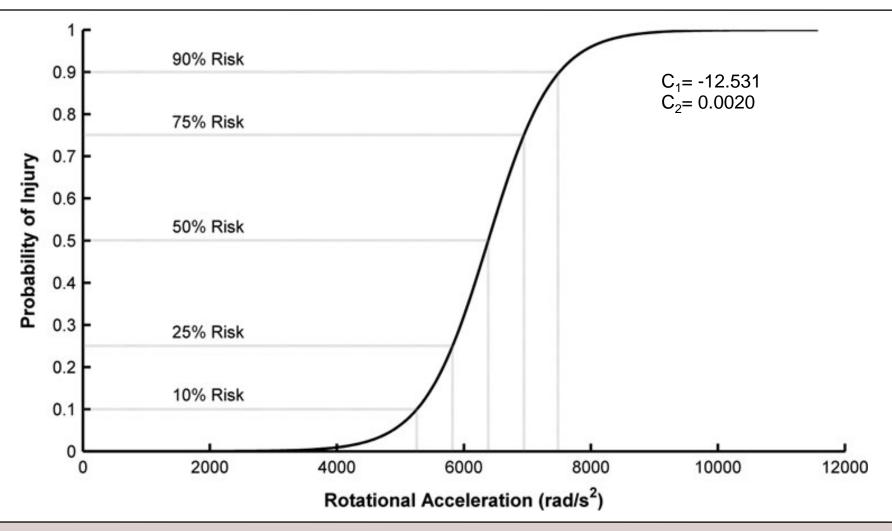


From Impact to Probability

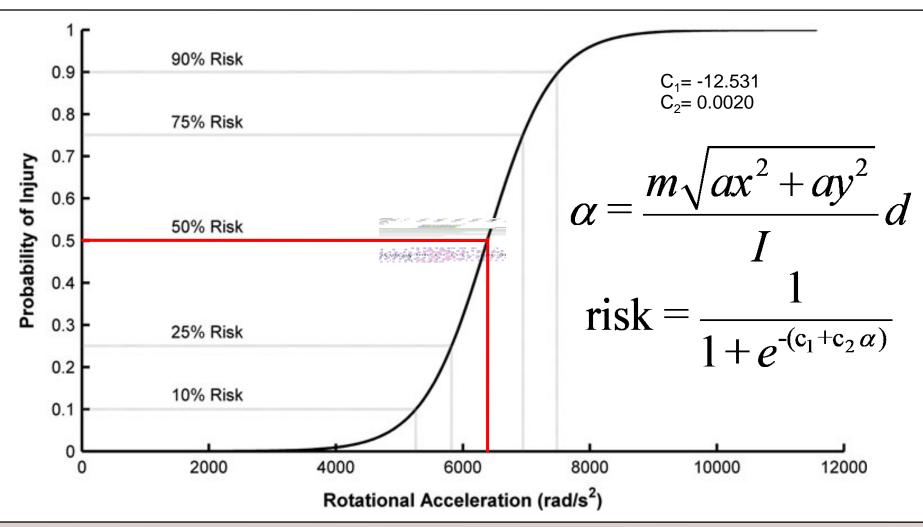
- "Rotational Head Kinematics in Football Impacts: An Injury Risk Function for Concussion"
 - S. Rowson *et al. Annals of Biomedical Engineering, Vol.* 40, No. 1, January 2012
- Rotational acceleration is important

$$\operatorname{risk} = \frac{1}{1 + e^{-(c_1 + c_2 \alpha)}}$$

Risk Function



Risk Function



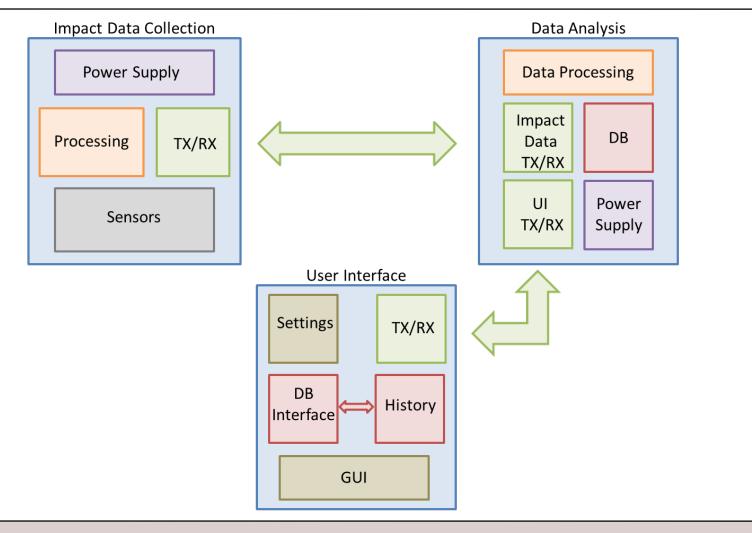
Our Solution: RCA

- Array of sensors in helmet padding
 - Continuous measurements
 - Variable impact thresholds
 - Wireless transmit on threshold trigger
- Base station
 - Database: Impact data & medical history
 - Concussion algorithm
 - Wireless transmit to UI & triggered helmet
- UI
 - Android device
 - Easy to interpret results within two seconds of impact

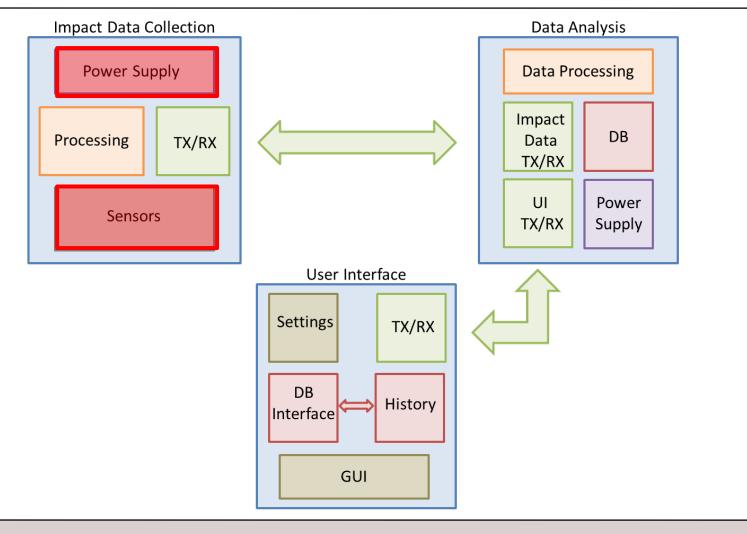
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Our Solution: Block Diagram



Sensor Network



Sensors

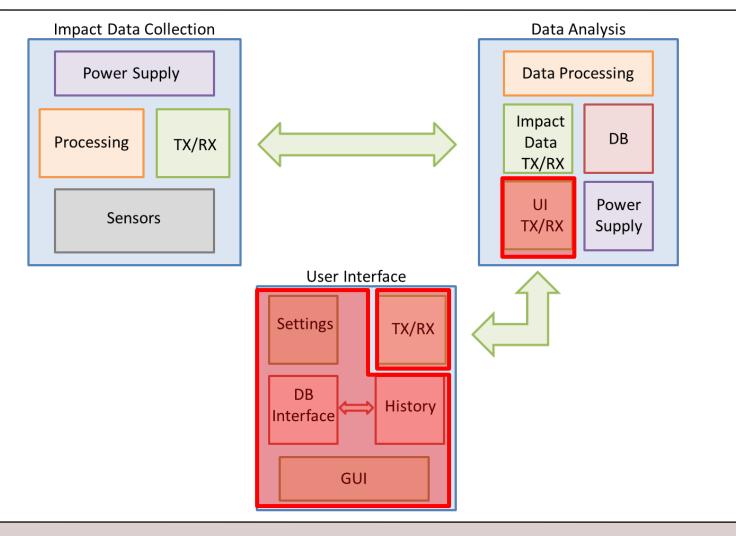
- Requirements
 - Accurate
 - Response time under 100 ms
 - Low power
 - Lightweight and secured safely
 - Players should not notice sensors
- Implementation
 - Accelerometers, Gyroscope
 - Successful Senior Design Projects
 - Motion Analyzer for Physical Therapy (2010) for Accelerometers
 - Personal Head-Up Display (2009) for Gyroscope



Power

- Requirements
 - 3.5 6 V in helmet
 - Safe, reliable and lightweight
 - Up to five hour run time
- Experience
 - Power supplies
 - Design experience in previous coursework
 - Theater design project

User Interface and Communication



UI

- Requirements
 - Easy to use
 - Deliver meaningful results
 - Medical staff
 - Coaching staff
- Implementation
 - Android Development



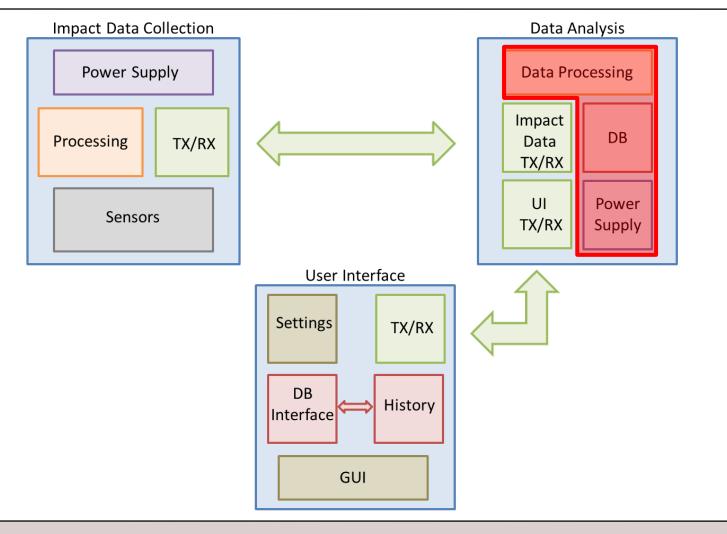
Tx/Rx for UI

- Requirements
 - Reliable
 - Response time under 500 ms
 - Easy to implement
- Implementation
 - Android WiFi/ Bluetooth Integration
 - Successful Senior Design Projects
 - BlueTag (2010) for Bluetooth
 - UMass Campus View (2010) for WiFi





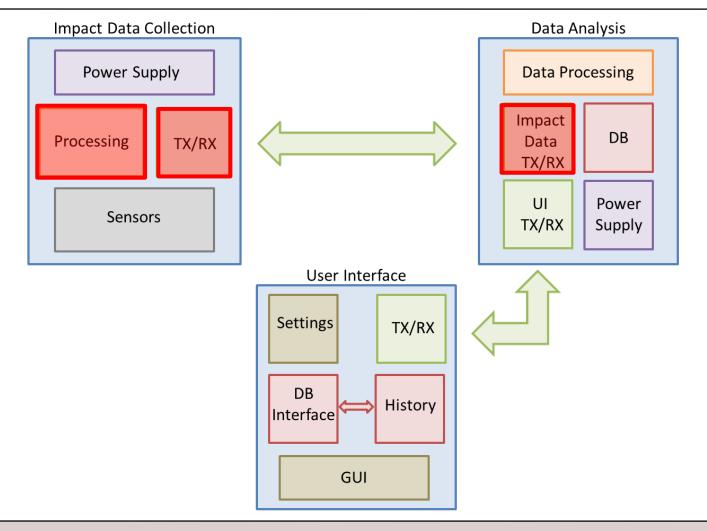
Data Processing and Storage



Data Processing and Storage

- Requirements
 - Calculates rotational acceleration
 - Determines probability of concussion
 - Output within 500 ms
 - Store all impact data efficiently
- Experience
 - Software development for Bose
 - Data organization and analysis algorithm development for ECM

Impact Processing and Communication



Impact Processing

- Requirements
 - Low power and lightweight
 - Inputs for at least 7 sensors
 - Tx/Rx Capable
 - Flash memory
- Experience
 - ATMega Microcontroller
 - Used in ECE 353
 - LED Cube



Impact Data Tx/Rx

- Requirements
 - Low power and lightweight
 - Effective range up to 150 m
 - Efficient data transfer rates
 - Secure
- Implementation
 - XBee
 - Successful Senior Design Projects
 - SAFE-T (2012) for XBee



Proposed MDR Deliverables

- Demonstration of Impact Data Collection
 - Accelerometer interfaced with processor
 - Helmet processor transmission
- Demonstration of Base Station/UI Interaction
 - Using test data
 - Receive from helmet
 - Run algorithm
 - UI able to receive and display test results